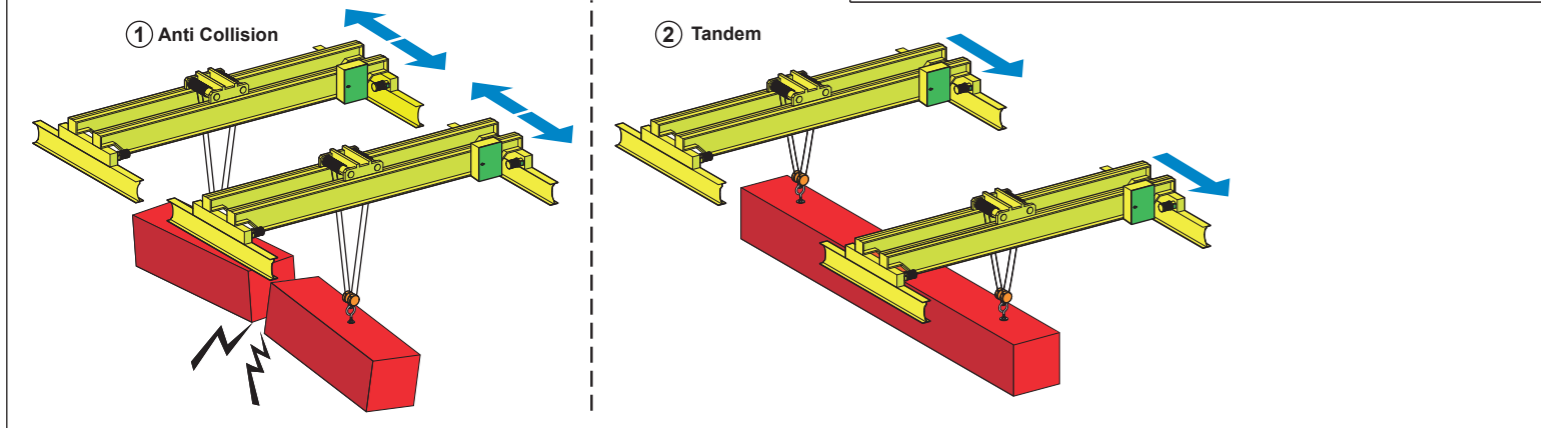


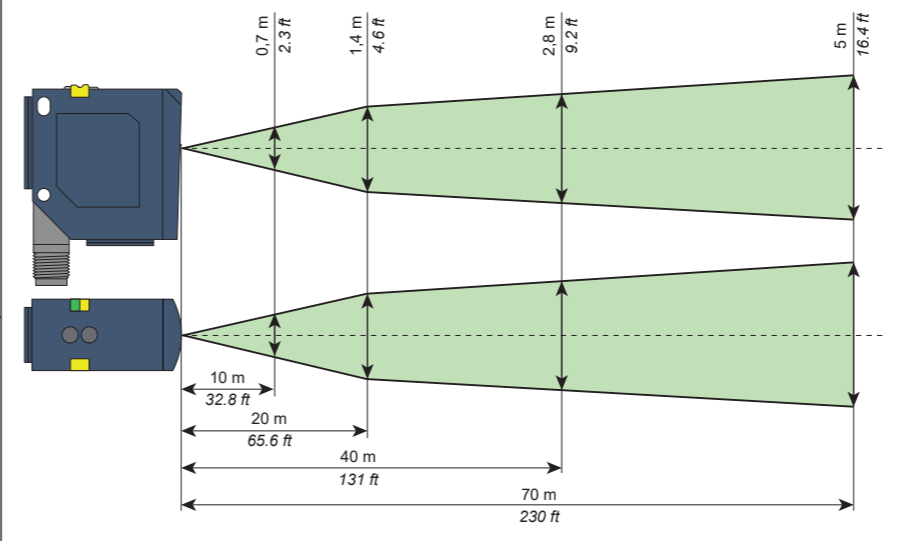
Anti Collision (1) and Tandem Sensor (2) for Over-head Cranes



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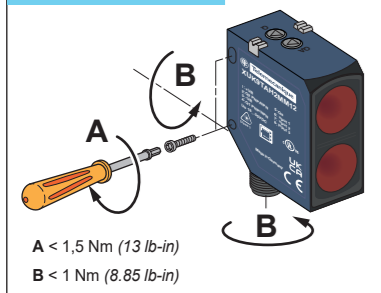
Prevention against other light beams in the colored area



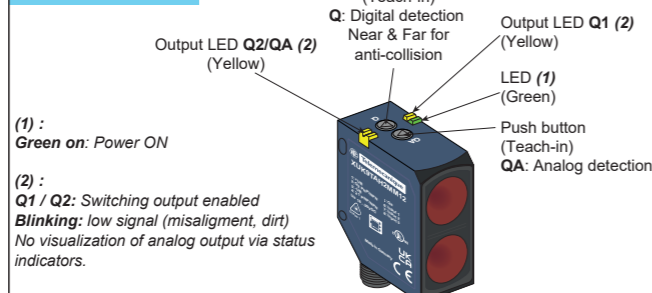
Characteristics

| | |
|---|---|
| Certification | CE - UKCA - cULus - Ecolab |
| Sensing distance (Reference material) | 0,3...70 m / 0,98...230 ft |
| Setting | Teach button or remote teach-in |
| Color of detection light beam | Laser class 1, red, 660 nm |
| Spot size of the light beam | see "Light beam size" curve |
| Wavelength | $\lambda = 660 \text{ nm}$ |
| Puls duration | $t \leq 8 \text{ ns}$ |
| Frequency | $f = 33 \text{ kHz}$ |
| Limit of radiant power pulse | $P_p < 310 \text{ mW}$ |
| Switching output | PNP or NPN |
| Analog output (Teachable only via button on the device) | 4...20 mA |
| Current consumption | $\leq 60 \text{ mA}$ |
| Switching capacity | $\leq 100 \text{ mA}$ |
| Switching frequency | $\leq 1500 \text{ Hz}$ |
| First-up delay | 300 ms max. |
| Response time | 10 ms max. |
| Recovery time | 10 ms max. |
| Ambient Temperature | Operating : - 30...+50 °C (-22...+122 °F) Storage : - 30...+60 °C (-22...+140 °F) |
| Power Voltage | Rated operational voltage: 24 Vdc Ripple p-p 10% maximum Operating range: 18...30 Vdc (including ripple) |
| Product Protection | Power supply : Reverse polarity protection Output: Short circuit protection |
| Protection class | IP67 conforming to EN/IEC 60529 IP69K conforming to DIN 40050 |
| Degree of protection | IP67 conforming to EN/IEC 60529 IP69K conforming to DIN 40050 |
| Vibration resistance | Frequency range: 10 Hz to 55 Hz Acceleration: 7 gn |
| Shock resistance | Peak acceleration: 10 gn Duration of the pulse: 11 ms |
| Material | Housing: ABS/PC, Lens: PMMA |

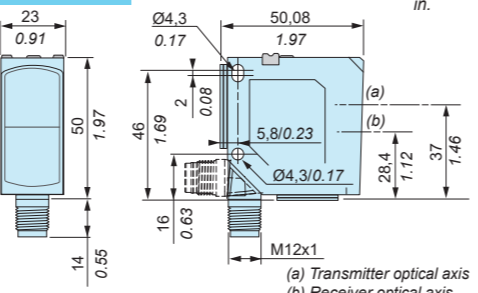
Tightening torques



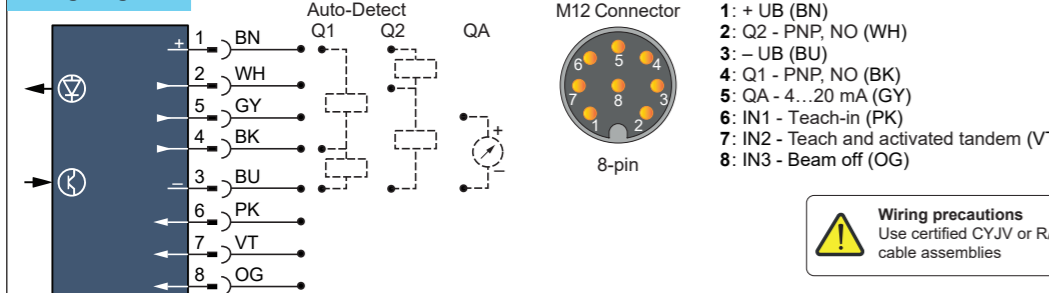
LEDs and Setting



Dimensions

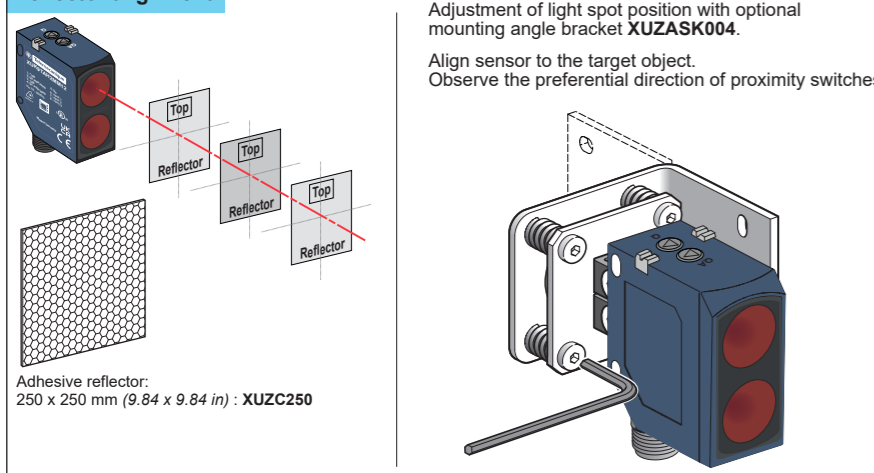


Wiring diagrams

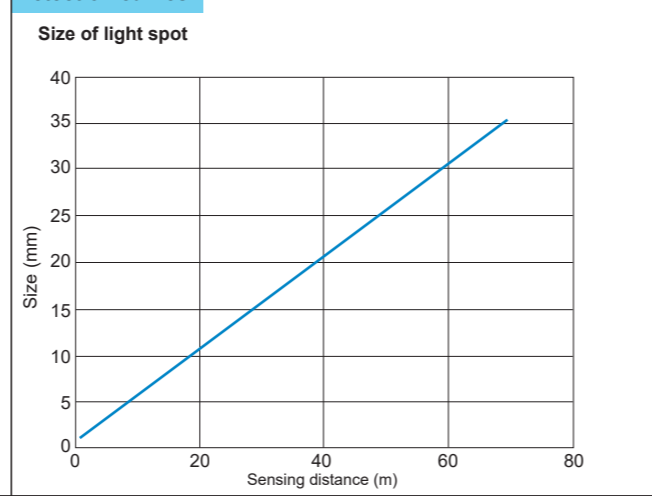


Wiring precautions
Use certified CYJV or R/C CYJV2 cable assemblies

Reflector alignment



Detection curves



WARNING
UNINTENDED EQUIPMENT OPERATION

- Comply with the wiring and configuration instructions.
- Clean the lens regularly, taking care not to scratch it.
- Check the connections and fixings during maintenance operations.

Failure to follow these instructions can result in death, serious injury or equipment damage.

CAUTION
HAZARD OF LASER RADIATION EXPOSURE

- Do not stare into the beam.
- Do not operate below - 30°C (- 22°F)
- Follow all operating instructions.

Failure to follow these instructions can result in injury or equipment damage.

CLASS 1 LASER PRODUCT (IEC 60825-1: 2014)
Complies with 21 CFR 1040.10 and 1040.11 except for deviations pursuant to Laser Notice No. 56 dated May, 2019

Electrical equipment should be installed, operated, serviced and maintained only by qualified personnel.
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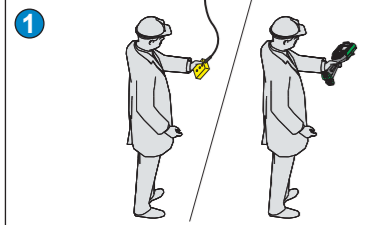
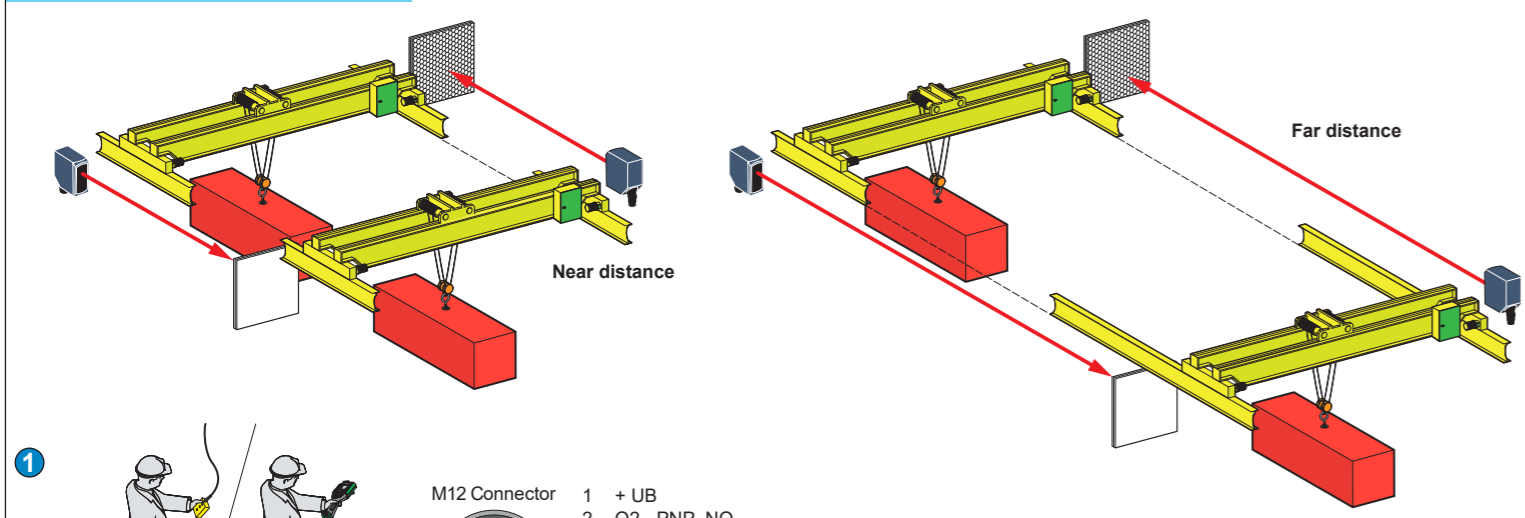
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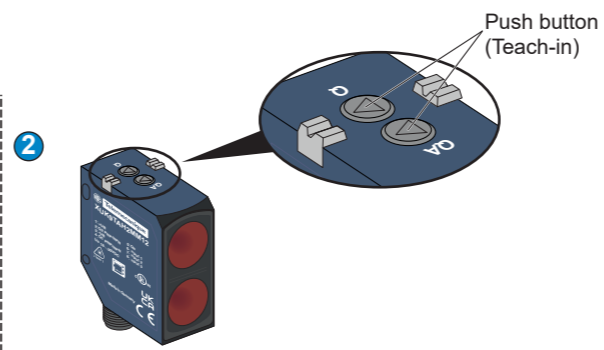
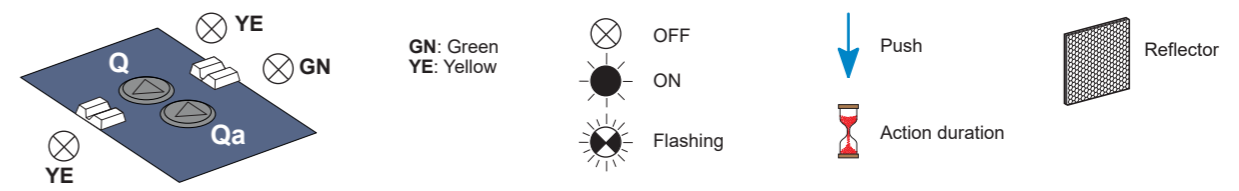
Setting for Anti-collision mode



M12 Connector 8-pin

| | |
|---|----------------------------------|
| 1 | + UB |
| 2 | Q2 - PNP, NO |
| 3 | GND |
| 4 | Q1 - PNP, NO |
| 5 | QA - 4...20 mA |
| 6 | IN1 - Teach-in |
| 7 | IN2 - Teach and activated tandem |
| 8 | IN3 - Beam off |

Setting



Teach-in Anti-Collision Mode through external wire

1.Step: First position
IN 1 = High > 3 sec and deactivation

2.Step: Second position
IN 1 = High > 32 ms and deactivation

The nearest of the two positions is taken as NEAR, the other is taken as FAR.
Set points NEAR and FAR are stored permanently even if you return from "Tandem Mode" in "Anti-Collision Mode".
Teach-in of the distance is done at the falling edge of the signal.
To set new distances for NEAR and FAR, a new complete teach-in needs to be done.
During teach, Q1 and Q2 are in slow mode condition (Q1=1, Q2=0)
If NEAR and FAR are too close together: previous setting is kept.
Time out to go back to operation mode between 1st step and 2nd step should be 30 minutes.

Teach-in Anti-Collision Mode by Push button

1.Step: First position
Press button Q for > 3 sec and release.
Feedback of status indicators.

2.Step: Second position
Press button Q and release
Feedback of status indicators

The nearest of the two positions is taken as NEAR, the other is taken as FAR.
Set points NEAR and FAR are stored permanently even if you return from "Tandem Mode" in "Anti-Collision Mode".
Teach-in of the distance is done when releasing the teach-in button.
During teach, Q1 and Q2 are in slow mode condition (Q1=1, Q2=0)
Time out to go back to operation mode between 1st step and 2nd step should be 5 minutes.
If NEAR and FAR are too close together: previous setting is kept.
No feedback via wire.

Feedback of teach-in and wire brake check

If low signal function is activated
Response to check wires not cut and teach is completed via external wire:
Q1 = Q2 = 3 pulses 100 ms high / 100 ms low (600 ms)



Feedback NEAR and FAR are too close:
Q1 = Q2 = 6 pulses 100 ms high / 100 ms low.



If low signal function is disabled
No feed back on Q1 and Q2.

Feedback of teach-in via button

- Teach Feedback:**
- Feedback teach success: Synchronous blinking of LEDs for 3 s.
 - Feedback NEAR and FAR are too close together: Fast asynchronous blinking of LEDs for 3 s.

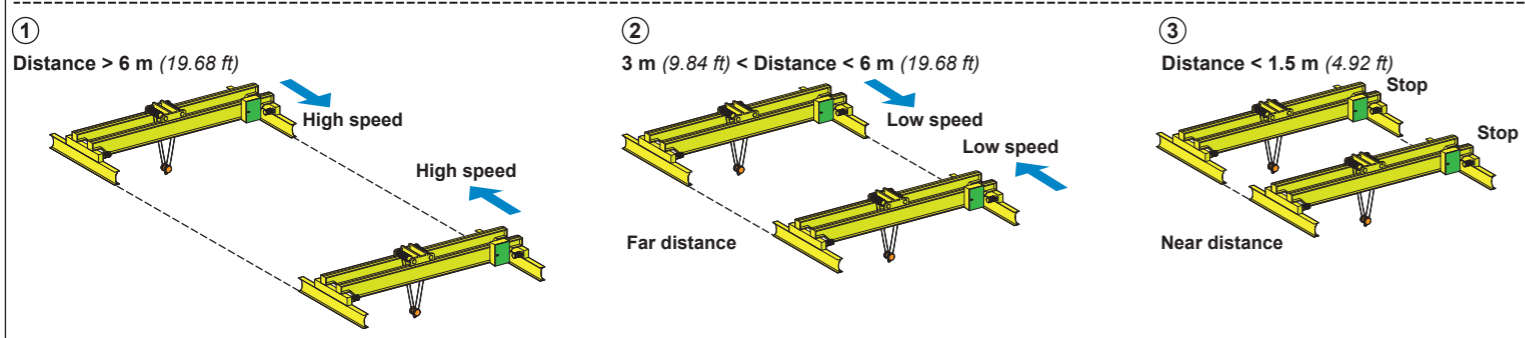
Output during anti-collision mode

Q1 = High / Q2 = High → High speed
Q1 = High / Q2 = Low → Slow
Q1 = Low / Q2 = Low → Stop

If low signal function is activated
Q1 = Low / Q2 = High → to less signal, reflector outside range or no reflector signal (*).

If low signal function is disabled
Q1 = high / Q2 = High → to less signal, reflector outside range or no reflector signal.

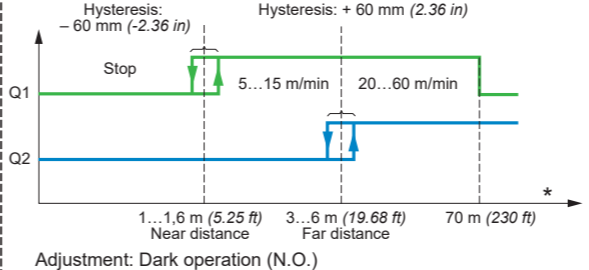
(* See Chapter B (page 3).



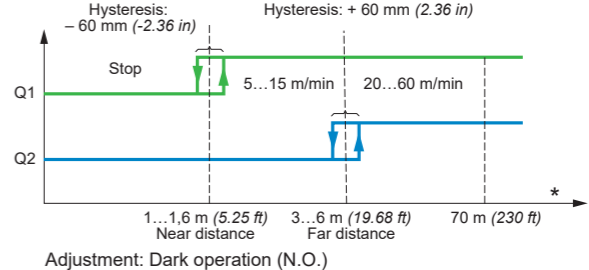
- ① If the distance between cranes is big enough, the speed of each crane can be **high** (20 ...60 m/min).
- ② If the distance is reduced (3 .. 6 m), the speed of each crane must be limited to **low** (5 ... 15 m/min).
- ③ If the distance is really too short (1 ... 1,5 m), then risk of collision so the 2 cranes must be **stopped**.

Anti-Collision Diagram

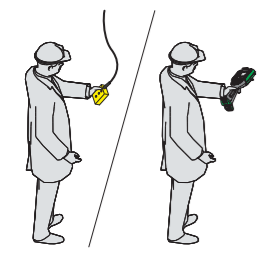
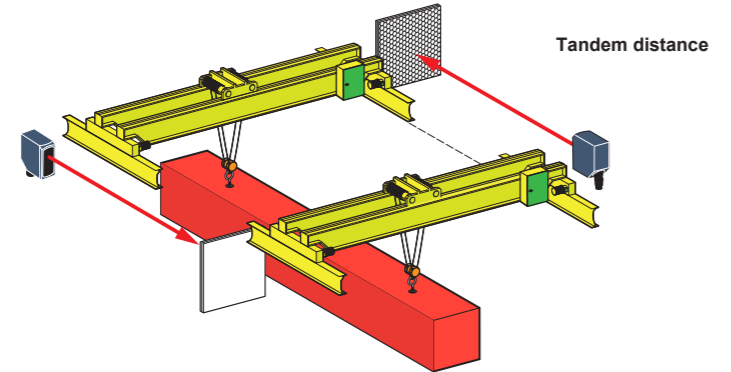
If low signal function is activated



If low signal function is disabled



Setting for Tandem mode



M12 Connector 8-pin

| | |
|---|----------------------------------|
| 1 | + UB |
| 2 | Q2 - PNP, NO |
| 3 | GND |
| 4 | Q1 - PNP, NO |
| 5 | QA - 4...20 mA |
| 6 | IN1 - Teach-in |
| 7 | IN2 - Teach and activated tandem |
| 8 | IN3 - Beam off |

Teach-in and activation of tandem mode through external wire

IN 2 = High
 The sensor teaches the distance of the tandem when activating IN 2 for at least 32 ms.
 The sensor puts a window around the taught-in distance.
 After deactivating IN 2 for at least 32 ms, the sensor goes back to anti-collision mode.
 The distance of the tandem mode is not stored permanently.

Feedback of teach-in and wire brake check

If low signal function activated
 Response that tandem mode is activated and to check that wires are not cut:
 • If tandem teach is **successful**
 Q1 = Q2 = permanent pulses 100 ms high / 100 ms low (600 ms)
 • If tandem teach is **not successful** (e.g no reflector present)
 Q1 = Q2 = 6 pulses 100 ms high / 100 ms low (1200 ms)
 If IN2 is deactivated during feedback, the feedback is stopped immediately.
If low signal function is disabled
 No feed back on Q1 and Q2 for successful teach and not successful teach.

Tandem Mode

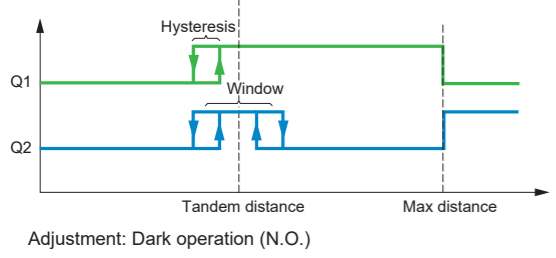
Q1 = Low / Q2 = Low → Outside window and closer than window closest position of the window.
 Q1 = High / Q2 = High → Inside the window
 Q1 = High / Q2 = Low → outside the window and farther than the farrest position of the window.

If low signal function (*) is activated
 Q1 = Low / Q2 = High → outside range → to less signal, reflector outside range.
If low signal function (*) is disabled
 Q1 = Low / Q2 = Low → outside range → to less signal, reflector outside range.

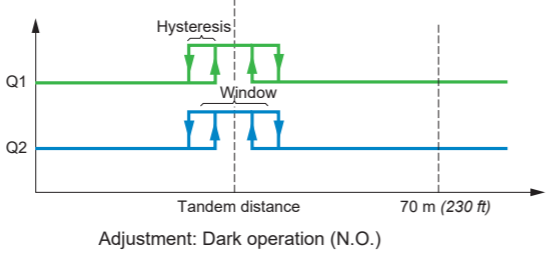
(*) This state can be disabled by pressing Q button for > 16 s See ①.

Tandem Diagram

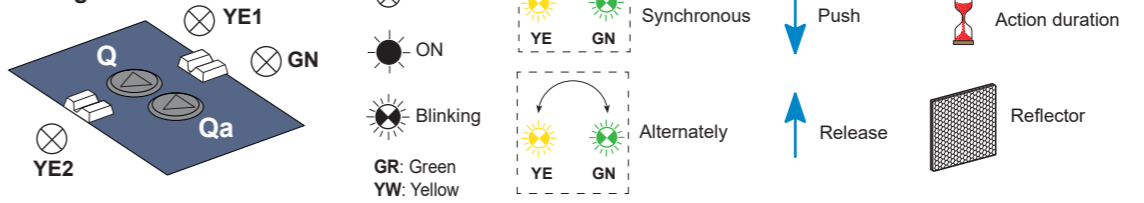
If low signal function is activated



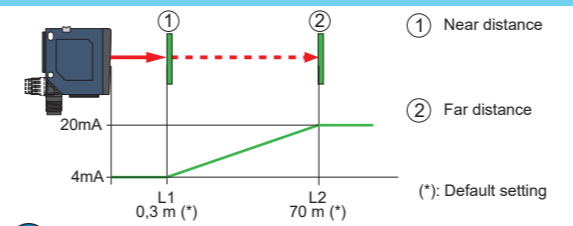
If low signal function is disabled



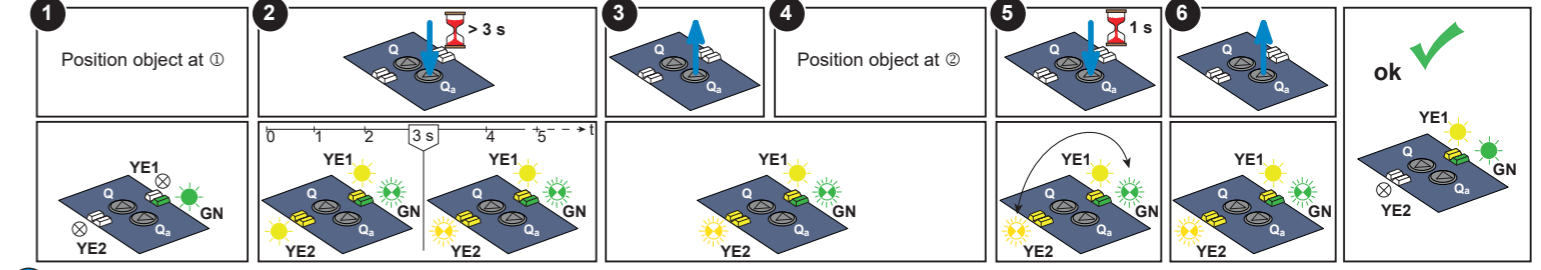
Setting



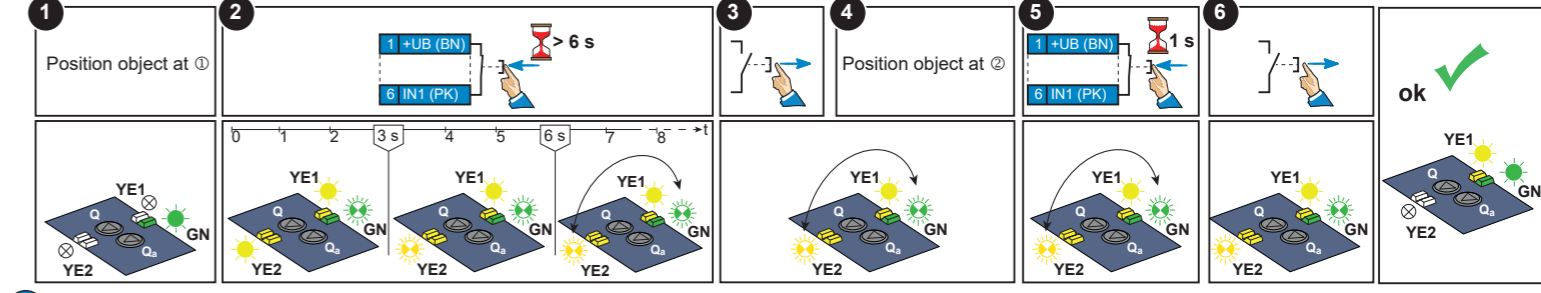
A Analog Output



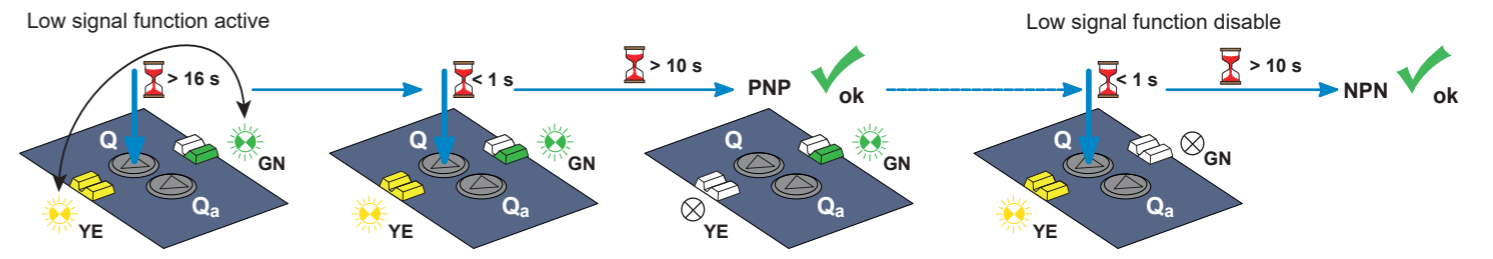
A1 Only via button QA



A2 Only via remote input IN1



B Low signal disable in case of contactors use (otherwise the use is PLC)

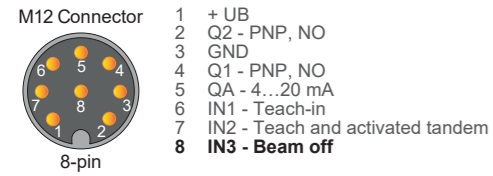


- Press Q > 16 s until green and yellow LED flash flash alternately.
- As long as the yellow and green LEDs are flashing, press the teach button for 1 s; the low signal function is active. The green LED shows the output status (PNP).
- When OK, do not push the button for 10 s. Setting is saved. Sensor is ready to operate.
- Press the teach button for 1 s; the low signal function is inactive. The yellow LED shows the output status (NPN). Every consecutive push/release will toggle the function, indicated by green or yellow LED.

To summarize:

- If the low signal is disabled:
- no feed back on Q1, Q2 after anticollision external teach or tandem teach.
 - Q1 and Q2 are modified, see "anticollision diagram" and "tandem diagram".

C Beam off Function



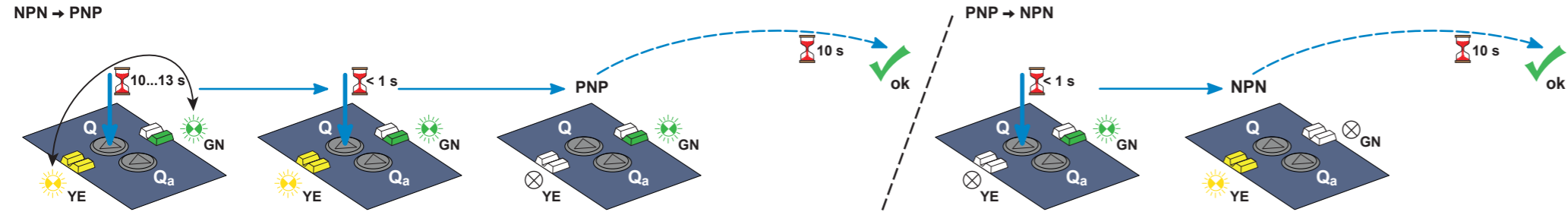
Activation:
 IN 3 = Low → Run (tandem or anti-collision)
 IN 3 = High → Diagnostic function, Laser off

- Response, if IN3 switches to high: (*)
- If Q1 is high → low (or low → high)
 - If Q2 is high → low (or low → high)
 - QA must keep its values.

Before beam-off, the cranes should be in Stop Condition!

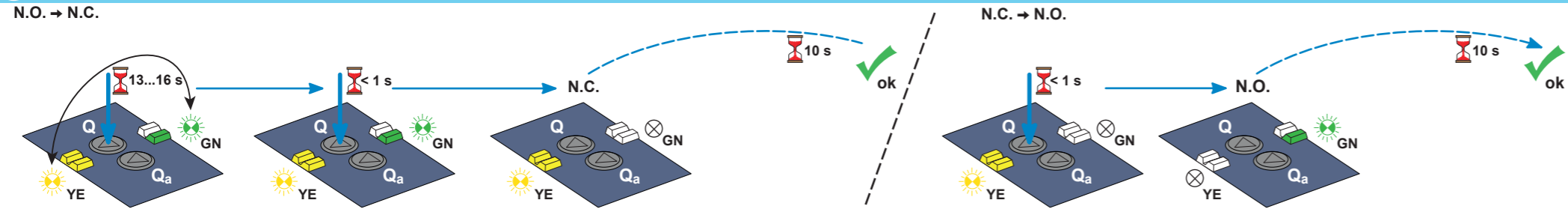
(*): The response time between activation (IN3) and response (Q1 or Q2) is less than 500 ms.

D Switching NPN / PNP



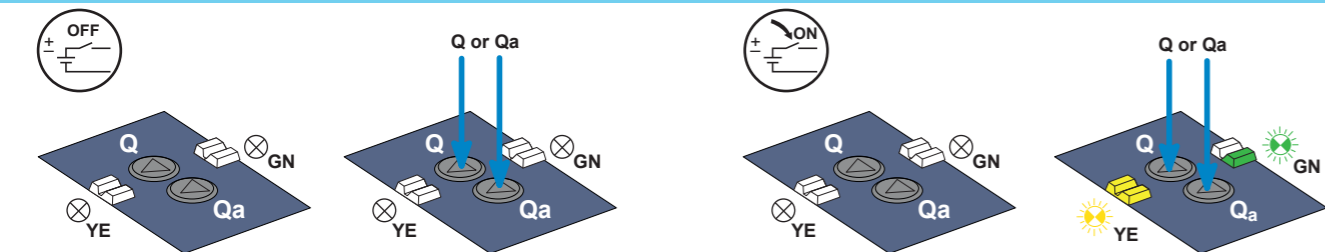
- Press Q 10 s...13 s until green and yellow LED flash alternatively.
- As long as the yellow and green LEDs are flashing, press the teach button for 1 s to invert the output. The green LED shows the output status (PNP).
- When OK, do not push the button for 10 s. Setting is saved. Sensor is ready to operate.
- Press the teach button for 1 s to invert the output. The yellow LED shows the output status (NPN). Every consecutive push/release will toggle the function, indicated by green or yellow LED.

E Switching N.O./N.C.



- Press Q 13 s...16 s until green and yellow LED flash at the same time.
- As long as the yellow and green LEDs are flashing, press the teach button for 1 s to invert the output. The yellow LED shows the output status (N.O.).
- When OK, do not push the button for 10 s. Setting is saved. Sensor is ready to operate.
- Press the teach button for 1 s to invert the output. The green LED shows the output status (N.C.). Every consecutive push/release will toggle the function, indicated by green or yellow LED.

F Default Setting



The sensor can be set back to the default setting.

The sensor must not be in tandem mode.

- Power supply OFF
- Press button Q or Qa
- Power supply ON
- Keep button pressed for 10 s until LEDs blink three times synchronously.