

ATV930U15N4

variable speed drive - ATV930 - 1,5kW - 400/480V -
with braking unit - IP21



Main

Range of product	Altivar Process ATV900
Product or component type	Variable speed drive
Device application	Industrial application
Device short name	ATV930
Variant	Standard version With braking chopper
Product destination	Asynchronous motors Synchronous motors
Mounting mode	Wall mount
EMC filter	Integrated conforming to EN/IEC 61800-3 category C2 with 50 m motor cable maxi Integrated conforming to EN/IEC 61800-3 category C3 with 150 m motor cable maxi
IP degree of protection	IP21 conforming to IEC 61800-5-1 IP21 conforming to IEC 60529
Degree of protection	UL type 1 conforming to UL 508C
Type of cooling	Forced convection
Supply frequency	50...60 Hz (+/- 5 %)
Network number of phases	3 phases
[Us] rated supply voltage	380...480 V (- 15...10 %)
Motor power kW	1.5 kW (normal duty) 0.75 kW (heavy duty)
Motor power hp	2 hp (normal duty) 1 hp (heavy duty)
Line current	3 A at 380 V (normal duty) 2.6 A at 480 V (normal duty) 1.7 A at 380 V (heavy duty) 1.5 A at 480 V (heavy duty)
Prospective line Isc	50 kA
Apparent power	2.2 kVA at 480 V (normal duty) 1.2 kVA at 480 V (heavy duty)
Continuous output current	4 A at 4 kHz (normal duty) 2.2 A at 4 kHz (heavy duty)
Maximum transient current	3.3 A during 60 s (heavy duty) 4.8 A during 60 s (normal duty)
Asynchronous motor control profile	Constant torque standard Variable torque standard Optimized torque mode
Synchronous motor control profile	Permanent magnet motor
Speed drive output frequency	0.1...599 Hz
Nominal switching frequency	4 kHz
Switching frequency	2...16 kHz adjustable 4...16 kHz with derating factor
Safety function	STO (safe torque off) SIL 3
Discrete input logic	16 preset speeds
Communication port protocol	Ethernet/IP Modbus serial Modbus TCP
Option card	Slot A : communication module for Profibus DP V1 Slot A : communication module for Profinet Slot A : communication module for DeviceNet Slot A : communication module for CANopen daisy chain RJ45

The information provided in this documentation contains general descriptions and/or technical characteristics of the performance of the products contained herein. This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications. It is the duty of any such user or integrator to perform the appropriate and complete risk analysis, evaluation and testing of the products with respect to the relevant specific application or use thereof. Neither Schneider Electric Industries SAS nor any of its affiliates or subsidiaries shall be responsible or liable for misuse of the information contained herein.

Slot A : communication module for CANopen SUB-D 9
Slot A : communication module for CANopen screw terminals
Slot A : communication module for EtherCAT
Slot A/slot B/slot C : digital and analog I/O extension module
Slot A/slot B/slot C : output relay extension module
Slot B : 5/12 V digital encoder interface module
Slot B : analog encoder interface module
Slot B : resolver encoder interface module

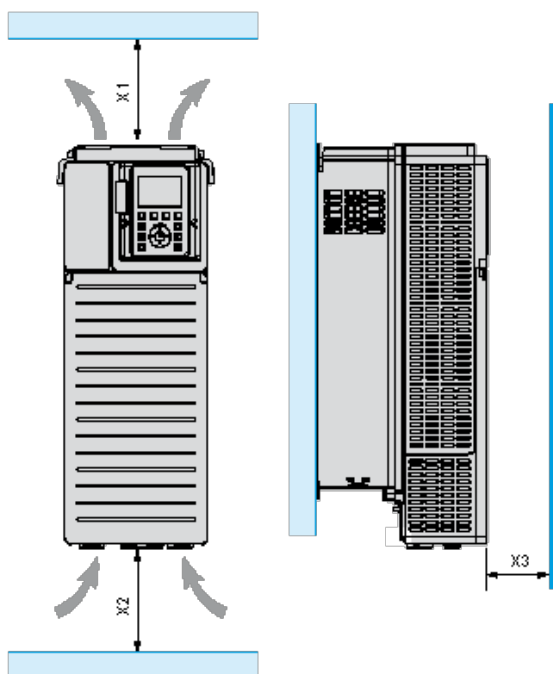
Complementary

Output voltage	<= power supply voltage
Motor slip compensation	Adjustable Automatic whatever the load Can be suppressed Not available in permanent magnet motor law
Acceleration and deceleration ramps	Linear adjustable separately from 0.01...9999 s
Braking to standstill	By DC injection
Protection type	Motor : thermal protection Motor : safe torque off Motor : motor phase break Drive : thermal protection Drive : safe torque off Drive : overheating Drive : overcurrent between output phases and earth Drive : overload of output voltage Drive : short-circuit protection Drive : motor phase break Drive : overvoltages on the DC bus Drive : line supply overvoltage Drive : line supply undervoltage Drive : line supply phase loss Drive : overspeed Drive : break on the control circuit
Frequency resolution	Display unit : 0.1 Hz Analog input : 0.012/50 Hz
Electrical connection	Control, screw terminal : 0.5...1.5 mm ² (AWG 20...AWG 16) DC bus, screw terminal : 2.5...6 mm ² (AWG 14...AWG 10) Line side, screw terminal : 2.5...6 mm ² (AWG 14...AWG 10) Motor, screw terminal : 2.5...6 mm ² (AWG 14...AWG 10)
Connector type	2 RJ45 (on the control block) for Ethernet IP/Modbus TCP 1 RJ45 (on the control block) for Modbus serial
Physical interface	2-wire RS 485 for Modbus serial
Transmission frame	RTU for Modbus serial
Transmission rate	10/100 Mbit/s for Ethernet IP/Modbus TCP 4.8, 9.6, 19.2, 38.4 kbit/s for Modbus serial
Exchange mode	Half duplex, full duplex, autonegotiation for Ethernet IP/Modbus TCP
Data format	8 bits, configurable odd, even or no parity for Modbus serial
Type of polarization	No impedance for Modbus serial
Number of addresses	1...247 for Modbus serial
Method of access	Slave for Modbus TCP
Supply	External supply for digital inputs : 24 V DC (19...30 V) current <= 1.25 mA (overload and short-circuit protection) Internal supply for reference potentiometer (1 to 10 kOhm) : 10.5 V DC +/- 5 % current <= 10 mA (overload and short-circuit protection) Internal supply for digital inputs and STO : 24 V DC (21...27 V) current <= 200 mA (overload and short-circuit protection)
Local signalling	3 mono/dual colour LED for local diagnostic 5 dual colour LED for embedded communication status 2 dual colour LED for communication module status 1 red LED for presence of voltage
Width	144 mm
Height	350 mm
Depth	206 mm
Product weight	4.5 kg
Analogue input number	3

Analogue input type	Software-configurable voltage AI1, AI2, AI3 : 0...10 V DC impedance 30 kOhm, resolution 12 bits Software-configurable current AI1, AI2, AI3 : 0...20 mA/4...20 mA impedance 250 Ohm, resolution 12 bits
Discrete input number	10
Discrete input type	Programmable DI1...DI8 : 24 V DC (≤ 30 V) impedance 3.5 kOhm Programmable as pulse input DI7, DI8 0...30 kHz : 24 V DC (≤ 30 V) Safe torque off STOA, STOB : 24 V DC (≤ 30 V) impedance > 2.2 kOhm
Input compatibility	Discrete input STOA, STOB : level 1 PLC conforming to EN/IEC 61131-2 Discrete input DI1...DI8 : level 1 PLC conforming to EN/IEC 61131-2 Pulse input DI7, DI8 : level 1 PLC conforming to IEC 65A-68
Discrete input logic	DI1...DI8, DI1...DI8 positive logic (source) : < 5 V (state 0) > 11 V (state 1) DI1...DI8, DI1...DI8 negative logic (sink) : > 16 V (state 0) < 10 V (state 1) DI7, DI8, DI7, DI8 positive logic (source) : < 0.6 V (state 0) > 2.5 V (state 1) STOA, STOB, STOA, STOB positive logic (source) : < 5 V (state 0) > 11 V (state 1)
Analogue output number	2
Analogue output type	Software-configurable voltage AQ1, AQ2, AQ1, AQ2 : 0...10 V DC impedance 470 Ohm, resolution 10 bits Software-configurable current AQ1, AQ2, AQ1, AQ2 : 0...20 mA impedance 500 Ohm, resolution 10 bits
Discrete output number	2
Discrete output type	Logic output DQ+ : 0...1 kHz (≤ 30 V) DC, < 100 mA Programmable as pulse output DQ+ : 0...30 kHz (≤ 30 V) DC, < 20 mA Logic output DQ- : 0...1 kHz (≤ 30 V) DC, < 100 mA
Sampling duration	Discrete input DI1...DI8 : 2 ms (+/- 0.5 ms) Pulse input DI7, DI8 : 5 ms (+/- 1 ms) Analog input AI1, AI2, AI3 : 1 ms (+/- 1 ms) Analog output AQ1, AQ2 : 5 ms (+/- 1 ms)
Accuracy	Analog input AI1, AI2, AI3 : +/- 0.6 % for a temperature variation 60 °C Analog output AQ1, AQ2 : +/- 1 % for a temperature variation 60 °C
Linearity error	Analog input AI1, AI2, AI3 : +/- 0.15 % of maximum value Analog output AQ1, AQ2 : +/- 0.2 %
Maximum switching current	Relay output R1 on inductive load ($\cos \phi = 0.4$ and $L/R = 7$ ms) : 2 A at 250 V AC Relay output R1 on inductive load ($\cos \phi = 0.4$ and $L/R = 7$ ms) : 2 A at 30 V DC Relay output R2, R3 on inductive load ($\cos \phi = 0.4$ and $L/R = 7$ ms) : 2 A at 250 V AC Relay output R2, R3 on inductive load ($\cos \phi = 0.4$ and $L/R = 7$ ms) : 2 A at 30 V DC Relay output R1 on resistive load ($\cos \phi = 1$) : 3 A at 250 V AC Relay output R1 on resistive load ($\cos \phi = 1$) : 3 A at 30 V DC Relay output R2, R3 on resistive load ($\cos \phi = 1$) : 5 A at 250 V AC Relay output R2, R3 on resistive load ($\cos \phi = 1$) : 5 A at 30 V DC
Relay output number	3
Relay output type	Configurable relay logic R1 : fault relay NO/NC electrical durability 100000 cycles Configurable relay logic R2 : sequence relay NO electrical durability 1000000 cycles Configurable relay logic R3 : sequence relay NO electrical durability 1000000 cycles
Refresh time	Relay output R1, R2, R3 : 5 ms (+/- 0.5 ms)
Minimum switching current	Relay output R1, R2, R3 : 5 mA at 24 V DC
Isolation	Between power and control terminals
Specific application	Process
IP degree of protection	IP21

Environment

insulation resistance	> 1 mOhm at 500 V DC for 1 minute to earth
noise level	54.5 dB conforming to 86/188/EEC
power dissipation in W	28 W (natural convection) at 380 V switching frequency 4 kHz 41 W (forced convection) at 380 V switching frequency 4 kHz
vibration resistance	1 gn ($f = 13...200$ Hz) conforming to IEC 60068-2-6 1.5 mm peak to peak ($f = 2...13$ Hz) conforming to IEC 60068-2-6
shock resistance	15 gn during 11 ms conforming to IEC 60068-2-27
volume of cooling air	38 m ³ /h
operating position	Vertical +/- 10 degree
THDI	≤ 48 % full load conforming to IEC 61000-3-12
electromagnetic compatibility	1.2/50 μ s - 8/20 μ s surge immunity test level 3 conforming to IEC 61000-4-5 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2

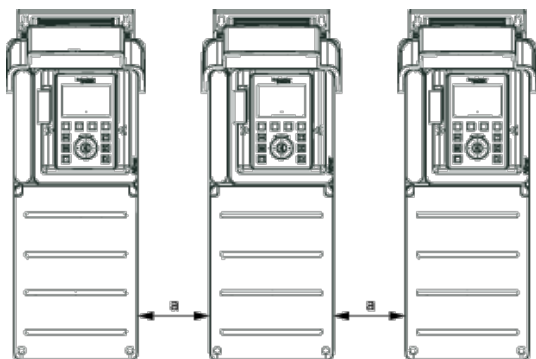


X1	X2	X3
$\geq 100 \text{ mm (3.94 in.)}$	$\geq 100 \text{ mm (3.94 in.)}$	$\geq 10 \text{ mm (0.39 in.)}$

- Mount the device in a vertical position ($\pm 10^\circ$). This is required for cooling the device.
- Do not mount the device close to heat sources.
- Leave sufficient free space so that the air required for cooling purposes can circulate from the bottom to the top of the drive.

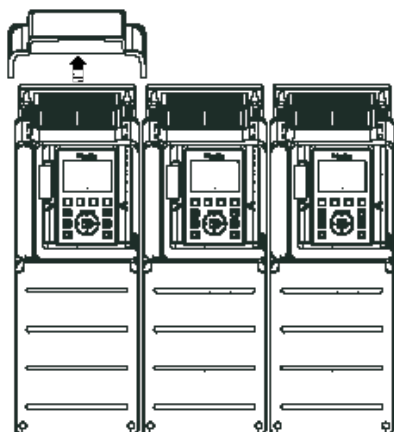
Mounting Types

Mounting Type A: Individual IP21



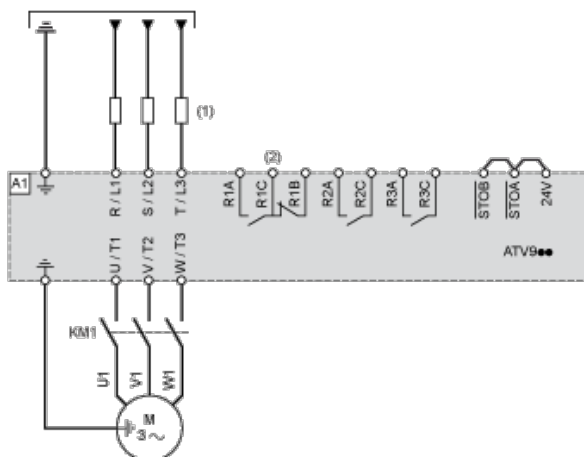
$a \geq 100 \text{ mm (3.94 in.)}$

Mounting Type B: Side by Side IP20



Mounting Type C: Individual IP20





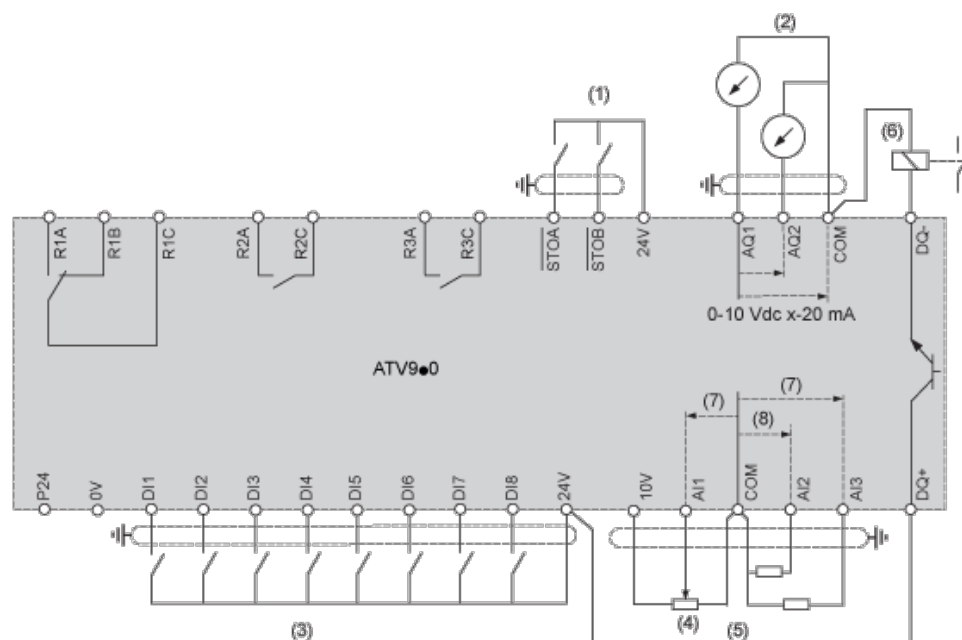
(1) Line choke if used

(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.

A1 : Drive

KM1 : Contactor

Control Block Wiring Diagram



(1) Safe Torque Off

(2) Analog Output

(3) Digital Input

(4) Reference potentiometer

(5) Analog Input

(6) Digital Output

(7) 0-10 Vdc, x-20 mA

(8) 0-10 Vdc, -10 Vdc...+10 Vdc

R1A, Fault relay

R1B,

R1C :

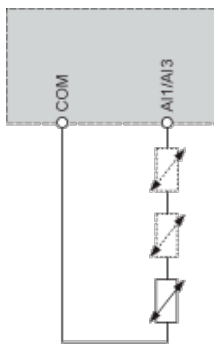
R2A, Sequence relay

R2C :

R3A, Sequence relay

R3C :

Sensor Connection



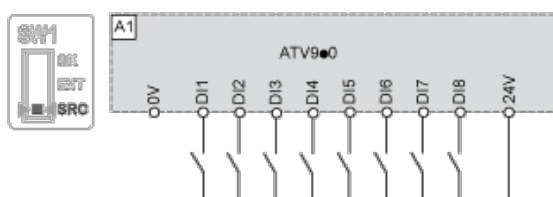
It is possible to connect either 1 or 3 sensors on terminals AI1 or AI3

Sink / Source Switch Configuration

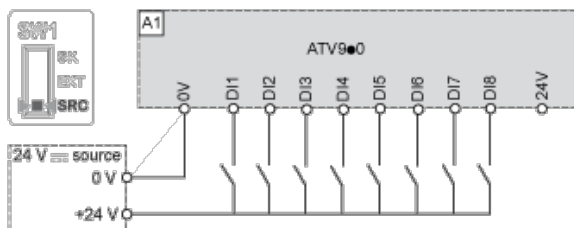
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

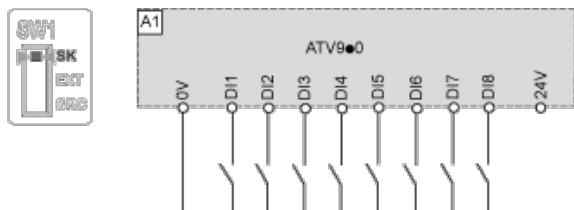
Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



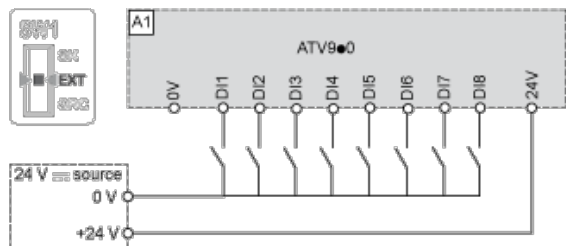
Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIIs



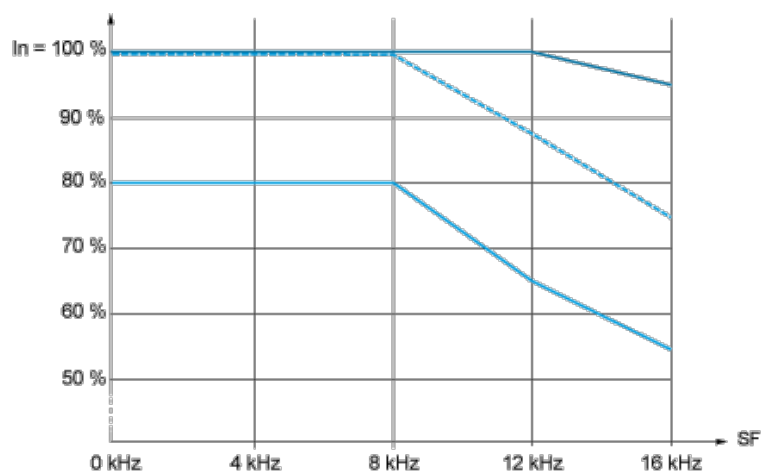
Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs



Switch Set to EXT Position Using an External Power Supply for the DIIs



Derating Curves



— 40 °C (104 °F) - Mounting type A, B and C

... 50 °C (122 °F) - Mounting type A, B and C

— 60 °C (140 °F) - Mounting type B and C

In : Nominal Drive Current

SF : Switching Frequency