

# ATV12PU30M3

variable speed drive ATV12 - 3kW - 3 hp - 3ph - 200..240V - on base plate



## Main

Range of product	Altivar 12
Product or component type	Variable speed drive
Product destination	Asynchronous motors
Product specific application	Simple machine
Assembly style	On base plate
Component name	ATV12
Quantity per set	Set of 1
EMC filter	Without EMC filter
Built-in fan	Without
Network number of phases	3 phases
[Us] rated supply voltage	200...240 V - 15...10 %
Motor power kW	3 kW
Communication port protocol	Modbus
Line current	19 A 200 V 15.9 A 240 V
Speed range	1...20
Transient overtorque	150...170 % of nominal motor torque depending on drive rating and type of motor
Asynchronous motor control profile	Quadratic voltage/frequency ratio Sensorless flux vector control Voltage/frequency ratio (V/f)
IP degree of protection	IP20 without blanking plate on upper part
Noise level	0 dB

## Complementary

Supply frequency	50/60 Hz +/- 5 %
Connector type	1 RJ45 Modbus on front face
Physical interface	2-wire RS 485 Modbus
Transmission frame	RTU Modbus
Transmission rate	4800 bit/s 9600 bit/s 19200 bit/s 38400 bit/s
Number of addresses	1...247 Modbus
Communication service	Read device identification (43) Read holding registers (03) 29 words Write single register (06) 29 words Write multiple registers (16) 27 words Read/write multiple registers (23) 4/4 words
Prospective line I <sub>sc</sub>	<= 5 kA
Continuous output current	12.2 A 4 kHz
Maximum transient current	18.3 A 60 s
Speed drive output frequency	0.5...400 Hz
Nominal switching frequency	4 kHz
Switching frequency	2...16 kHz adjustable 4...16 kHz with derating factor
Braking torque	Up to 70 % of nominal motor torque without braking resistor
Motor slip compensation	Adjustable Preset in factory
Output voltage	200...240 V 3 phases
Electrical connection	Terminal 5.5 mm <sup>2</sup> AWG 10 L1, L2, L3, U, V, W, PA, PC

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Tightening torque	1.2 N.m
Insulation	Electrical between power and control
Supply	Internal supply for reference potentiometer 5 V DC 4.75...5.25 V 10 mA overload and short-circuit protection Internal supply for logic inputs 24 V DC 20.4...28.8 V 100 mA overload and short-circuit protection
Analogue input number	1
Analogue input type	Configurable current AI1 0...20 mA 250 Ohm Configurable voltage AI1 0...10 V 30 kOhm Configurable voltage AI1 0...5 V 30 kOhm
Discrete input number	4
Discrete input type	Programmable LI1...LI4 24 V 18...30 V
Discrete input logic	Negative logic (sink) > 16 V < 10 V 3.5 kOhm Positive logic (source) 0...< 5 V > 11 V
Sampling duration	20 ms +/- 1 ms logic input 10 ms analogue input
Linearity error	+/- 0.3 % of maximum value analogue input
Analogue output number	1
Analogue output type	Software-configurable voltage AO1 0...10 V 470 Ohm 8 bits Software-configurable current AO1 0...20 mA 800 Ohm 8 bits
Discrete output number	2
Discrete output type	Logic output LO+, LO- Protected relay output R1A, R1B, R1C 1 C/O
Minimum switching current	5 mA 24 V DC logic relay
Maximum switching current	2 A 250 V AC inductive cos phi = 0.4 L/R = 7 ms logic relay 2 A 30 V DC inductive cos phi = 0.4 L/R = 7 ms logic relay 3 A 250 V AC resistive cos phi = 1 L/R = 0 ms logic relay 4 A 30 V DC resistive cos phi = 1 L/R = 0 ms logic relay
Acceleration and deceleration ramps	Linear from 0 to 999.9 s S U
Braking to standstill	By DC injection <= 30 s
Protection type	Line supply overvoltage Line supply undervoltage Overcurrent between output phases and earth Overheating protection Short-circuit between motor phases Against input phase loss in three-phase Thermal motor protection via the drive by continuous calculation of I <sup>2</sup> t
Frequency resolution	0.1 Hz display unit Converter A/D, 10 bits analog input
Time constant	20 ms +/- 1 ms for reference change
Marking	CE
Operating position	Vertical +/- 10 degree
Height	184 mm
Width	140 mm
Depth	100.2 mm
Product weight	1.6 kg
Discrete and process manufacturing	Commercial equipment : mixer Commercial equipment : other application Textile : ironing
Motor starter type	Variable speed drive

## Environment

electromagnetic compatibility	Electrical fast transient/burst immunity test level 4 EN/IEC 61000-4-4 Electrostatic discharge immunity test level 3 EN/IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 EN/IEC 61000-4-3 Immunity to conducted disturbances level 3 EN/IEC 61000-4-6 Surge immunity test level 3 EN/IEC 61000-4-5 Voltage dips and interruptions immunity test EN/IEC 61000-4-11
electromagnetic emission	Radiated emissions environment 1 category C2 EN/IEC 61800-3 2...16 kHz shielded motor cable Conducted emissions EN/IEC 61800-3

product certifications

CSA  
C-Tick  
GOST  
NOM  
UL

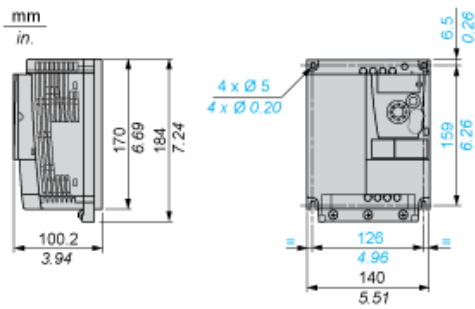
vibration resistance	1 gn EN/IEC 60068-2-6 13...200 Hz 1.5 mm peak to peak EN/IEC 60068-2-6 3...13 Hz drive unmounted on symmetrical DIN rail
shock resistance	15 gn EN/IEC 60068-2-27 11 ms
relative humidity	5...95 % without condensation IEC 60068-2-3 5...95 % without dripping water IEC 60068-2-3
ambient air temperature for storage	-25...70 °C
ambient air temperature for operation	40...60 °C with current derating 2.2 % per °C -10...40 °C protective cover from the top of the drive removed
operating altitude	<= 1000 m without derating > 1000...3000 m with current derating 1 % per 100 m

## Offer Sustainability

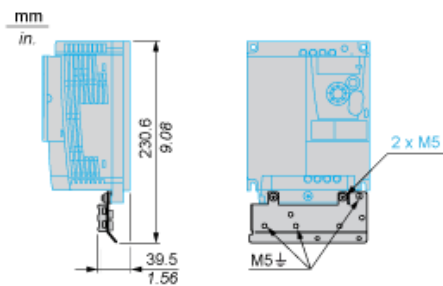
Sustainable offer status	Not Green Premium product
RoHS (date code: YYWW)	Compliant - since 0901 - Schneider Electric declaration of conformity
REACH	Reference not containing SVHC above the threshold

## Dimensions

### Drive without EMC Conformity Kit

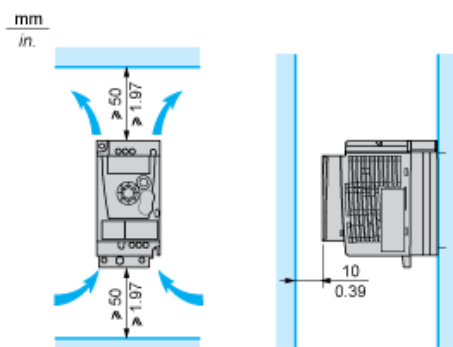


### Drive with EMC Conformity Kit

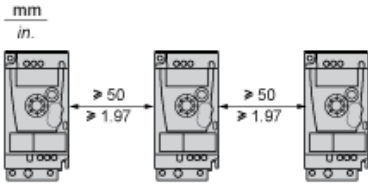


## Mounting Recommendations

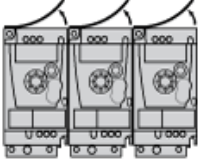
### Clearance for Vertical Mounting



### Mounting Type A

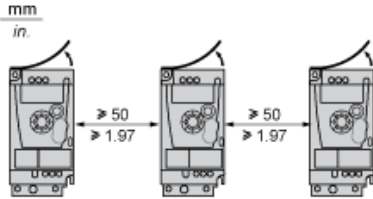


### Mounting Type B



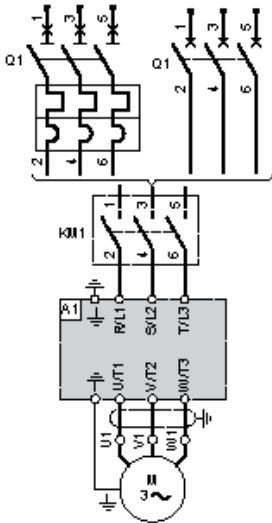
Remove the protective cover from the top of the drive.

### Mounting Type C



Remove the protective cover from the top of the drive.

### Three-Phase Power Supply Wiring Diagram



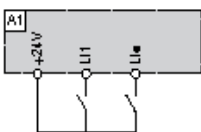
A1 Drive

KM1 Contactor (only if a control circuit is needed)

Q1 Circuit breaker

### Recommended Schemes

#### 2-Wire Control for Logic I/O with Internal Power Supply

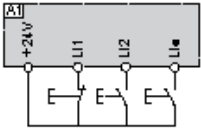


L11 : Forward

L1e : Reverse

A1 : Drive

### 3-Wire Control for Logic I/O with Internal Power Supply



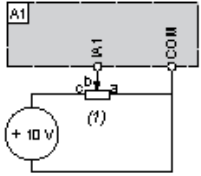
L1 : Stop

L12 : Forward

L1e : Reverse

A1 : Drive

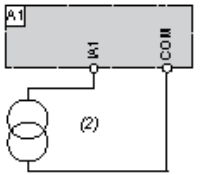
### Analog Input Configured for Voltage with Internal Power Supply



(1) 2.2 kΩ...10 kΩ reference potentiometer

A1 : Drive

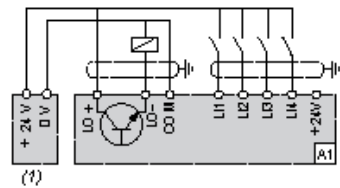
### Analog Input Configured for Current with Internal Power Supply



(2) 0-20 mA 4-20 mA supply

A1 : Drive

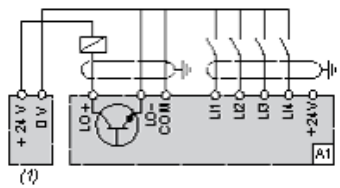
### Connected as Positive Logic (Source) with External 24 vdc Supply



(1) 24 vdc supply

A1 : Drive

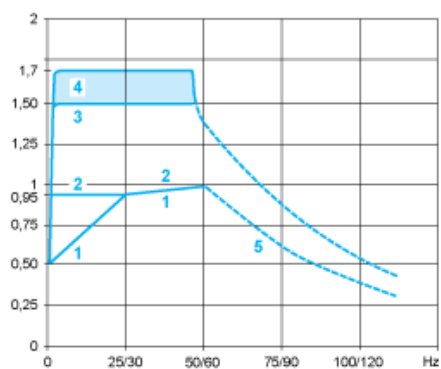
### Connected as Negative Logic (Sink) with External 24 vdc supply



(1) 24 vdc supply

A1 : Drive

### Torque Curves



- 1 : Self-cooled motor: continuous useful torque **(1)**
- 2 : Force-cooled motor: continuous useful torque
- 3 : Transient overtorque for 60 s
- 4 : Transient overtorque for 2 s
- 5 : Torque in overspeed at constant power **(2)**

- (1) For power ratings  $\leq 250$  W, derating is 20% instead of 50% at very low frequencies.
- (2) The nominal motor frequency and the maximum output frequency can be adjusted from 0.5 to 400 Hz. The mechanical overspeed capability of the selected motor must be checked with the manufacturer.